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FAILURE MODES EFFECTS ANALYSIS (FMEA) - CRITICAL HARDWARE

: ASSY, ELECTRO-MAGNETIC DAMPER

NUMBER: M8-1MR-9M004-X

33U.6661.007

330.6661.007

9/1/95

SUBSYSTEM NAME: MECHANICAL - EDS

	*
PART NAME VENDOR NAME	PART NUMBER VENDOR NUMBER
DOCKING MECHANISM ASSEMBLY	330,5316,003-05
NPO-ENERGIA	33U.5316.003-05
ASSY, ELECTRO-MAGNETIC DAMPER	33U.6661.006
NPO-ENERGIA	33U 6661 006

REVISION:

PART DATA

EXTENDED DESCRIPTION OF PART UNDER ANALYSIS: HIGH ENERGY ELECTRO-MAGNETIC DAMPER ASSEMBLY

NPO-ENERGIA

REFERENCE DESIGNATORS:

QUANTITY OF LIKE ITEMS: 3 THREE (ONE PER BALLSCREW PAIR)

FUNCTION:

LAU

SAU

SRU

A HIGH ENERGY SLECTRO-MAGNETIC DAMPER IS LOCATED BETWEEN EACH ROD OF THE BALLSCREW PAIRS AND IS ENGAGED BY A SOLENOID DRIVEN MECHANICAL LOCK (CLUTCH) DEVICE. ALL THREE DAMPER ASSEMBLIES ARE INTERCONNECTED THROUGH THE KINEMATIC CHAIN TO DAMP OUT RELATIVE PITCH AND YAW ROTATIONAL VELOCITIES OF THE RING FOLLOWING CAPTURE.

SERVICE IN BETWEEN PLIGHT AND MAINTENANCE CONTROL: VISUAL INSPECTION, SERVICEABILITY CONTOL, DOCKING WITH CALIBRATING DOCKING MECHANISM.

MAINTAINABILITY

REPAIR METHOD - REPLACEMENT.

REFERENCE DOCUMENTS: 33U.6661.006

33U.6661.007 33U.6316.003-05 33U.6321.004



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I FAILURE MODES EFFECTS ANALYSIS (FMEA) - CIL FAILURE MODE

NUMBER: M8-1MR-8M0Q4-01

REVISIONS

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9/1/95

SUBSYSTEM NAME: MECHANICAL - EDS

LRU: DOCKING MECHANISM ASSEMBLY

CRITICALITY OF THIS

ITEM NAME: ASSEMBLY, HIGH ENERGY DAMPER

FAILURE MODE: 2/2

FAILURE MODE:

JAMMING, INCREASED RESISTANCE

MISSION PHASE:

00

ON-CABIT

VEHICLE/PAYLOAD/KIT EFFECTIVITY: 104 ATLANTIS

CAUSE:

CONTAMINATION, STRUCTURAL FAILURE DUE TO MECHANICAL SHOCK, VIBRATION, OR MANUFACTURE/MATERIAL DEFECT

CRITICALITY 1/1 DURING INTACT ABORT ONLY? NO

CRITICALITY 1R2 DURING INTACT ABORT ONLY (AVIONICS ONLY)? WA

REDUNDANCY SCREEN

A) N/A

B) WA

C) N/A

PASS/FAIL RATIONALE:

A)

N/A

6)

NVA

C) N/A

METHOD OF FAULT DETECTION:

VISUAL OBSERVATION - NO CAPTURE INDICATION DURING DOCKING. TELEMETRY DATA ASSOCIATED WITH MOVEMENT OF THE RING (BALLSCREW MISALIGNMENT) IS AVAILABLE TO GROUND PERSONNEL FOR EVALUATION OF A JAMMED DAMPER.

- FAILURE EFFECTS -

(A) SUBSYSTEM:
A JAMMING OF ONE DAMPER WILL PREVENT/RESTRICT PITCH AND YAW MOVEMENT OF
ITS ASSOCIATED BALL NUT PAIR AND SUBSEQUENTLY, RESTRICT PITCHYAW
MOVEMENT OF THE DOCKING RING. AN INCREASED RESISTANCE COULD BE
OVERCOME BY THE POWER OF THE DOCKING MECHANISM ASSEMBLY ALLOWING
CAPTURE TO OCCUR. HOWEVER, TOTAL JAMMING OF A HIGH ENERGY DAMPER
ASSEMBLY WOULD PRECLUDE CAPTURE. DAMAGE SUSTAINED BY THE MECHANISM,

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FAILURE MODES EFFECTS ANALYSIS (FMEA) — CIL FAILURE MODE NUMBER: M8-1MR-8M004- 01

DUE TO EXCESSIVE CAPTURE LOADS, COULD PREVENT EXTENSION OR RETRACTION OF THE DOCKING RING.

(B) INTERFACING SUBSYSTEM(S):

EXCESSIVE LOADS INCURRED DURING DOCKING AS THE RESULT OF A JAMMED HIGH ENERGY DAMPER COULD PROPAGATE TO EXTERNAL AIRLOCK AND ORBITER STRUCTURE.

(C) MISSION:

WORST CASE, HIGH LOADS AND MISALIGNMENT WILL MAKE CAPTURE IMPOSSIBLE. EXCESSIVE LOADS INCURRED DURING CONTACT COULD CAUSE DAMAGE TO ORBITER AND MIR DOCKING MECHANISMS RESULTING IN THE LOSS OF CAPABILITY TO EXTEND OR RETRACT DOCKING RING. INABILITY TO PERFORM CAPTURE OR MOVE RING TO MATE BOTH MECHANISMS WILL PRECLUDE DOCKING CAPABILITIES RESULTING IN LOSS OF ORBITER/MIR MISSION CAPABILITIES.

(D) CREW, VEHICLE, AND ELEMENT(S):

EXCESSIVE LOADS EXPERIENCED DURING CAPTURE AS THE RESULT OF A JAMMED DAMPER COULD CAUSE EXTENSIVE DAMAGE TO BOTH ORBITER AND MIR DOCKING MECHANISMS. CREW AND ORBITER STRUCTURE ARE UNAFFECTED BY THESE LOADS.

(E) FUNCTIONAL CRITICALITY EFFECTS:

N/A

DESIGN CRITICALITY (PRIOR TO OPERATIONAL DOWNGRADE, DESCRIBED IN F): 2/2

(F) RATIONALE FOR CRITICALITY CATEGORY DOWNGRADE:

N/A (THERE ARE NO WORKAROUNDS TO CIRCUMVENT THIS FAILURE.)

-DISPOSITION RATIONALE-

(A) DESIGN:

DÉSIGN OF THE DAMPERS PROVIDES SUFFICIENT FREEPLAY SETWEEN SURFACES TO ALLOW FOR TEMPERATURE EXPANSION AND TO PREVENT JAMMING. CLUTCH SURFACES ARE MADE OF STEEL ALLOYS AND ARE AN INTER-MESHING TOOTH DESIGN. THE DAMPING PORTION IS A MAGNETIC FIELD DEVICE. GRAPHITE LUBRICATION IS PROVIDED TO PREVENT MOVING SURFACES FROM STICKING. ALL DAMPER PARTS HAVE A SAFETY FACTOR NO LESS THAN 1.4.

LOAD ANALYSIS HAS SHOWN THAT THE MAXIMUM DOCKING LOADS INCURRED AS THE RESULT OF THIS FAILURE WILL NOT EXCEED EXTERNAL AIRLOCK/ORBITER STRUCTURAL LIMITS.

(B) TEST:

DOCKING MECHANISM ACCEPTANCE TESTS:

- 1. INSPECTION SERVICEABILITY TEST (SENSOR FUNCTIONAL TEST) OPERATIONAL CHECKOUT OF THE ELECTROMAGNETIC DAMPERS IS
 PERFORMED THROUGH CAPTURE SENSOR PER STEP 13 OF INSTRUCTION
 33U.6201.008-05 PM-3.
- 2. VIBRORESISTENT TEST APDS SUBJECTED TO THE FOLLOWING VIBRATION LEVELS FOR 2 MINUTES PER AXIS:



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FAILURE MODES EFFECTS ANALYSIS (FMEA) - CIL FAILURE MODE

NUMBER: M8-1MR-BM004-01

FREQUENCY (HZ)	SPECTORAL DENSITY ACCELERATION
FROM 20 TO 80	INCREASING, 3DB OCTAVE TO 0,04G2/HZ
FROM 80 TO 350	PERMANENT 0.04G ² /HZ
FROM 350 TO 2000	DECREASING 3DB OCTAVE WITH 0.04G2/HZ

SUBSEQUENT TO THIS TEST AN ENGINEERING INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE AND A FUNCTIONAL CHECK IS PERFORMED, PER ATP #1 ABOVE, TO VERIFY PROPER OPERATION OF THE ELECTROMAGNETIC DAMPERS.

- 3. DOCKING MECHANISM CHECKOUT (STATIC) TEST A HIGH ENERGY DAMPER FUNCTIONAL PERFORMANCE TEST IS PERFORMED AS PART OF THE CHECKOUT OF THE DOCKING MECHANISM. WITH THE GUIDE RING IN ITS INITIAL POSITION IT IS ROTATED ABOUT THE Y AND Z AXES AND THE MOMENT WAS MEASURED WITH AND WITHOUT HIGH ENERGY DAMPERS ENGAGED. THIS TEST VERIFIES THAT THE DOCKING RING RETURNS TO INITIAL POSITION WITH DAMPERS OFF AND DOES NOT RETURN TO INITIAL POSITION WITH DAMPERS ON. A JAMMED DAMPER WOULD BE DETECTED AT THIS TIME.
- 4. THERMO VACUUM TEST DOCKING OF THE MECHANISM IS THERMALLY CYCLED, UNDER LOAD CONDITIONS, FROM +20°C TO -50'-55°C TO +50'+65°C TO +20°C IN A VACUUM AT 10°⁴ TO 10°⁵ TORR. DWELL AT EACH TEMPÉRATURE AND BETWEEN OPÉRATIONS AT EACH TEMPÉRATURE IS A MINIMUM OF 60 MINUTES AFTER STABILIZATION. OPERATIONS INCLUDES PERFORMING DOCKING WHICH IS ACCOMPLISHED AT A SPEED OF 0.15M/SEC BETWEEN THE SIMULATOR AND MOVEABLE PLATFORM (CONTAINING THE DOCKING MECHANISM). AT EACH TEMPÉRATURE ELECTRO-MAGNÉTIC DAMPERS ARE TURNED ON FOLLOWING RING EXTENSION AND CURRENT TO EACH IS MEASURED. PROPER OPERATION OF THESE DAMPERS IS VERIFIED FOR A TEMPÉRATURE RANGE OF -50°C'-55°C TO 50°C'-55°C.
- 5. CONTROLLED DOCKING TEST CONTROLLED DOCKING IS PERFORMED UNDER LOAD CONDITIONS. PROPER RING PERFORMANCE WILL VERIFY HIGH ENERGY DAMPING OPERATIONS.

DOCKING MECHANISM QUALIFICATION TESTS:

1. TRANSPORTABILITY STRENGTH TEST - SHIPPING LOADS ARE SMULATED ON A VIBRATING TABLE TO VERIFY THAT THE DOCKING MECHANISM WILL NOT BE DAMAGED DURING SHIPMENT. THIS TEST IS CONDUCTED UNDER THE CONDITIONS CONTAINED IN THE FOLLOWING TABLE.

VIBRATION	VIDRATION	FREQUENCY SUBBAND, HZ				TOTAL TEST		
ACCELER	ACCELER	5-7 7-15 15-30 30-40 40-60 DUF				DUR/	ATION	
DIRECTION	AMPLITUDE		TEST DURATION, MIN					MIN
ALONG X-AXIS	1.4	-	4	1			-	4
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	1.2	76	93	32	61	39	5	7
ALONG Y-AXIS		-	4	_	— .	-	1	4
' - 	1.0	13	16	7	10	7		53
ALONG Z-AXIS			4	-		4	_	4
1 1120,13 2 14	· 1.0	32	40	16	26	16	2	10

FAILURE MODES EFFECTS ANALYSIS (FMEA) — CIL FAILURE MODE
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SUBSEQUENT TO THIS TEST AN INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE AT WHICH TIME A JAMMED DAMPER WOULD BE DETECTED.

- 2. SHOCK AND SAWTOOTH LOADING STRENGTH TEST DOCKING MECHANISM IS SUBJECTED TO 20G TERMINAL SAWTOOTH SHOCK PULSES IN EACH AXIS, 3 PULSES IN EACH DIRECTION FOR A TOTAL OF 6 PULSES/AXIS, AFTER COMPLETION AN INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE. A JAMMED DAMPER WOULD BE DETECTED AT THIS TIME.
- 3. VIBRATION STRENGTH TEST APDS SUBJECTED TO THE FOLLOWING VIBRATION LEVELS IN EACH AXIS FOR A 400 SECOND DURATION.

FREQUENCY (HZ)	SPECTORAL DENSITY ACCELERATION
FROM 20 TO 80	INCREASING, 3DB OCTAVE TO 0.087GZ/HZ
FROM 80 TO 350	CONSTANT 0.067G ² /HZ
FROM 350 TO 2000	DECREASING 3DB OCTAVE WITH 0.067G2/HZ

SUBSEQUENT TO THIS TEST AN ENGINEERING INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE AT WHICH TIME A JAMMED DAMPER WOULD BE DETECTED.

- 4. APDS SERVICEABILITY TEST IN A SIX-DEGREE-OF-FREEDOM DYNAMIC TEST-THE SIX-DEGREE-OF-FREEDOM DYNAMIC TEST VERIFIES APDS DOCKING AND UNDOCKING OPERATIONS UNDER CLOSE-TO-FULL-SCALE CONDITIONS. STATIC MOTION OF ENTITIES IS SIMULATED UNDER SPECIFIC INJERTIAL AND GEOMETRICAL PARAMETERS FOR VARIOUS INITIAL CONDITIONS FOR MIRVSHUTTLE DOCKING. A TOTAL OF 20 DOCKINGS IS PERFORMED. ABSORPTION OF ENERGY OF RELATIVE MOVEMENT DURING EACH DOCKING WILL DETECT A JAMMED DAMPER. SUBSEQUENT TO THIS TEST AN ENGINEERING INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE.
- 5. TARGET SERVICE LIFE TEST TESTS ARE PERFORMED TO VERIFY PROPER DOCKING OPERATIONS OVER ITS LIFE OF 100 DOCKINGS. PROPER OPERATION OF THE DAMPERS VERIFIED DURING 100 DOCKING CYCLES (FOR MC821-0087-1001/-3001 UNITS ONLY). FOR MC821-0087-2001, -4001, & -5001 UNITS PROPER OPERATION VERIFIED DURING 388 CYCLES (44 VACUUMA.OAD CYCLES, 16 LOAD CYCLES, & 324 NO-LOAD CYCLES). SUBSEQUENT TO THIS TEST AN ENGINEERING INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE.
- 6. COLD AND HEAT RESISTANCE TEST DOCKING OF THE MECHANISM IS THERMALLY CYCLED FROM +20°C TO -50'-55°C TO +50'+55°C TO +20°C IN A VACUUM AT 10°4 TO 10°5 TORR. DWELL AT EACH TEMPERATURE AND BETWEEN OPERATIONS AT EACH TEMPERATURE IS A MINIMUM OF 60 MINUTES AFTER STABILIZATION. FIVE CYCLES WERE PERFORMED AGAINST THE GUIDE RING EXTEND AND FINAL POSITION MECHANICAL STOPS FOR 10 SECONDS EACH. DURING EACH DOCKING, AS SHOWN IN THE FOLLOWING TABLE, A JAMMED DAMPER WOULD BE DETECTED.

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FAILURE MODES EFFECTS ANALYSIS (FMEA) — CIL FAILURE MODE NUMBER: M8-1MR-5M004-01

SEQ NO.	DOCKING RATE, M/S	SIMULATOR ROTATIONAL ANGLE		TEMP	VOLTAGE	PRESS
		PITCH	ROLL	°C	VOLTS	CHECKOUT
1	0.10	<u>0°</u>	0-	25 +/- 10	23	YES
2	0.10	00	40	25 +/-10	34	NO
3	0.12	4°	4°	25 +/-10	27	, NO
4*			<u></u>	+60+/-5		· YES_
4	0.10	4.	0°	+50+/-5	27	YES
5*	+==+			-(60+/-5)	_	YES _
5	0.10	4*	Ç.	-(30+/-5)	27	YES
6*		****		+60+/-5		YES
6	0.12	0-	4°	+50+/-5	23	YE\$
7-			<u> </u>	-(60+/-5)	<u> </u>	YES_
7	0.10	0-	49	-(30 +/-5)	23	YES
8.		_	<u> </u>	+60+/-5	_	YEŞ
8	0.12	4°	4º	50 +/-5	34	YES
g•	<u> </u>	— .		-(60+/-5)		YES
9	0.12	4 °	4°	-(30 +/-5)	34	YES
10"				+60+/-5		YES
10	0.10	4°	0°	+50+/-5	27	YES
11*		-		-(60+/-5)		YES
11	0.10	O°	4°	-(30 +/-5)	27	YES
12*				+60+/-5		YES
12"	0.10	Ο̈́	4°	+50+/-5	27	YES
13'				-(60+/-6)		YES
13"	0.12	4°	4*	-(30 +/-5)	27	YES
14'				+60+/-5		YES
14"	0.12	4°	4-	+50+/-5	27	YES
15*	0.12	4*	4°	+25+/-10	23	YES

AFTER COMPLETION AN INSPECTION IS PERFORMED TO IDENTIFY BROKEN OR LOOSE HARDWARE.

7. CONTROL DISASSEMBLY - UPON COMPLETION OF ALL QUAL TESTING THE DOCKING MECHANISM IS DISMANTLED AND ELECTRO-MAGNETIC DAMPER ASSEMBLIES ARE CHECKED FOR EVIDENCE OF WEAR OR FAILURE.

OMRSD - TURNAROUND CHECKOUT TESTING IS ACCOMPLISHED IN ACCORDANCE WITH OMRSO.

(C) INSPECTION:
RECEIVING INSPECTION
COMPONENTS ARE SUBJECTED TO A 100% RECEIVING INSPECTION PRIOR TO INSTALLATION.

CONTAMINATION CONTROL
CORROSION PROTECTION PROVISIONS AND CONTAMINATION CONTROL VERIFIED BY
INSPECTION, CHECK OF ROOM CLEANLINESS; PARTS WASHING AND OTHER



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FAILURE MODES EFFECTS ANALYSIS (FMEA) -- CIL FAILURE MODE

NUMBER: M8-1MR-BM004-01

OPERATIONS OF THE TECHNOLOGICAL PROCESS WHICH PROVIDES CLEANLINESS ARE VERIFIED BY INSPECTION.

CRITICAL PROCESSES

ANODIZING, HEAT TREATING, CHEMICAL PLATING, SOLDERING, AND CURING VERIFIED BY INSPECTION.

ASSEMBLY/INSTALLATION

TORQUE, ADJUSTMENTS AND TOLERANCES ACCORDING TO TECHNICAL REQUIREMENTS OF THE DRAWINGS ARE VERIFIED BY INSPECTION.

TESTING

ATP/QTP/OMRSD TESTING VERIFIED BY INSPECTION.

HANDLING/PACKAGING

HANDLING/PACKAGING PROCEDURES AND REQUIREMENT FOR SHIPMENT VERIFIED BY INSPECTION.

(D) FAILURE HISTORY:

DATA ON TEST FAILURES, UNEXPLAINED ANOMALIES, AND OTHER FAILURES EXPERIENCED DURING GROUND PROCESSING OF ODS DOCKING MECHANISMS CAN BE FOUND IN PRACADATA BASE.

(E) OPERATIONAL USE:

NONE FOR A COMPLETE JAMMING OF THE DAMPER. HOWEVER AN INCREASE IN RESISTANCE CAN BE OVERCOME BY THE EXTERNAL FORCES OF DOCKING.

- APPROVALS -

DESIGN ENGINEER DESIGN MANAGER

AMSS ABAN

NASA SUBSYSTEM MANAGER

M. NIKOLAYEVA A. SOUBCHEV