CRITICAL ITEMS LIST

PROJECT: SRMS (-5 MCIU INSTALLED)
ASS'Y NOMENCLATURE: MOTOR HODULE

SYSTEM: MECHANICAL ARM SUBSYSTEM ASS'Y P/N: \$1140E1214 SKEET: 1

FHEA REF.	FHEA REV.	NAME, GTY, & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	HOWR / FUNC. RATIONALE FOR ACCEPTANCE 1/1 CRETICALITY SCREENS: N/A		
4175	O	COMMUTATION SCANNER GTY-6 P/N 51140E1295	HODE: ERRATIC COMMUTATION IN PRIME AND BACKUP MODES. CAUSE(S): (1) LOSS OF PLATTING ON CODE WHEEL.	AUTOBRAKES ARE APPLIED. ARH COMES TO REST. LOSS OF REGULAR COMMUTATION. ABILITY TO START THE JOINT IN PRIME AND BACK-UP MAY BE LOST. ARM MAY TAKE AN UNEXPECTED TRAJECTORY. LOSS OF ALL MODES. WORST CASE UNEXPECTED MOTION. ELECTRICALLY FROZEN. CREW ACTION REQUIRED. REDUNDANT PATHS REMAINING N/A	THE JOINT COMMUTATION SCANNER ASSEMBLY (CSA) IS A MAJOR BOUGHT-GUT-PART WHICH IS SUPPLIED BY BEI MOTION SYSTEMS AND MEETS OR EXCEEDS THE REQUIREMENTS OF SPECIFICATION SPAR-SG.467. CODE WHEELS ARE MANUFACTURED PER BEI PROCEDURE 90SA12224. THE BASE METAL WHEEL IS CHROME-PLATED BY AN OUTSIDE VENDOR, AND RETURNED TO BEI. PHOTO-RESIST IS USED TO MASK AREAS WHICH MILL REMAIN BLACK, WHILE AREAS WHICH ARE TO BE REFLECTIVE ARE STRIPPED OF BLACK CHROME TO EXPOSE THE GOLD SURFACE. THIS PROCESS INSURES GOOD ADMESTON.		
							PAGE 221 OF 471
			i.		1 1 5 c freque	ALE SING	
PREPARED B	j 17: <u>t</u>	IFMG	SUPERCEDING DAT	E: NONE	DATE: 11 JUL 91		

RMS/MECH - 317

PROJECT: SRMS (-5 MCJU INSTALLED)
ASS'Y NOMENCLATURE: NOTOR MODULE

SYSTEM: MECHANICAL ARM SUBSYSTEM ASS'Y P/N: \$1140E1214

SHEET: __2

O COMMITATION O COMMITATION SINANCE GIV-6 P/N 51140E1295 NODE: COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MODES. COMMITATION BACKUP MAY THE JOINT IN PRIME AND BACKUP MAY BE LOST GREGULAR ON STATE THE JOINT IN PRIME AND BACKUP MAY BE LOST ARM MAY TAKE AN UNEXPECTED TO THE FOLLOWING ACCEPTANCE EVS COMMITATION PAIR MOTOR MODULE ASSEMBLY COMSIST ASSEMBLY MOTOR ASSEMBLY TACHOMETER CO ALL OF WHICH ARE EXPOSED TO AND CITED TO ACCEPTANCE EVS SUBJECTED TO THE FOLLOWING ACCEPTANCE EVS O VIBRATION: O THERMAL VACUUM: *85 DEGREES C TO -25 CVCLES) 1 X 10°*5 TOR THE MOTOR MODULE IS INSTALLED IN THE JOINT IS EXPOSED TO ANOTHER ACCEPTANCE EVS VIBRATION O THE MOTOR MODULE ASSEMBLY TACHOMETER AND DURATION. A TYPICAL MOTOR MODULE ASSEMBLY TACHOMETER AND SUBJECTED TO THE MOTOR MODULE ASSEMBLY TACHOMETER AND SUBJECTED TO TO SOME DEGREE OF QUALIFICATION VEFTOR. THE MOTOR MODULE ESSENDED OVERNAL VACUUM: *485 DEGREES C TO -25 CVCLES) 1 X 10°*5 TOR THE MOTOR MODULE ASSEMBLY TACHOMETER AND SUBJECTED TO THE MOTOR MODULE ASSEMBLY TACHOMETER AND SUBJECTED TO SOME DEGREE OF QUALIFICATION VEFTOR. THE MOTOR MODULE TESTS: O VIBRATION: O THERMAL VACUUM: *496 DEGREE C TO -36 IN 10°*6 TOR O SHOCK: 20G/11 MS - 3 AXES (6 DIRECTIO O HUMIDITY: TESTED IN SHOULDER JOINT HU D EMC: MIL-STD-441 AS MODIFIED BY SL-E-	
CS02, CS06, CE01, RE02(N/B), RS0 FLIGHT CHECKOUT PORS OPS CHECKLIST (ALL VEHICLES) JSC 169.	TEST BY THE VEHDOR DULE ASSEMBLY IS IRONMENT: ENCE TABLE B DEGREES C (1.5 IS ASSEMBLY AND AGAIN ICH INCLUDES APPROXIMATE LEVEL AND ICH INCLUDES APPROXIMATE

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PREPARED BY:

MFWG

SUPERCEDING DATE: NONE

RMS/MECH - 318

DATE: 11 JUL 91

CIL REV: 0

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CRITICAL ITEMS LIST

PROJECT: SRMS (-5 MCIU INSTALLED)
ASS'Y NOMENCLATURE: MOYOR MODULE

				ST HOMENULATURE: AL	ASS'Y P/N: 51140E1214 SHEET:
FMEA REF.	FMEA REV.	NAME, GTY, & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	HOWR / FUNC. RATIONALE FOR ACCEPTANCE 1/1 CRITICALITY SCREENS: N/A
4175	0	COMMUTATION SCANNER GTY-6-P/N 51140E1295	MODE: ERRATIC COMMUTATION IN PRIME AND BACKUP MODES. CAUSE(S): (1) LOSS OF PLATING ON CODE WHEEL.	AUTOBRAKES ARE APPLIED. ARM COMES TO REST. LOSS OF REGULAR COMMUTATION. ABILITY TO START THE JOINT IN PRIME AND BACK-UP MAY BE LOST. ARM MAY TAKE AM UNEXPECTED TRAJECTORY. LOSS OF ALL MODES. MORST CASE UNEXPECTED MOTION. ELECTRICALLY FROZEN. CREW ACTION REQUIRED. REDUMBANT PATHS REMAINING M/A	UNITS ARE MAJOR BOUGHT OUT PARTS, MANUFACTURED, ASSEMBLED AND TESTED TO SPAR DRAWINGS AND SPECIFICATIONS UNDER DOCUMENTED OUALITY CONTROLS. THESE CONTROLS ARE EXERCISED THROUGHOUT DESIGN PROCUPEMENT, PLANNING, PROCESSING, FABRICATION, ASSEMBLY QUALIFICATION AND ACCEPTANCE TESTING, MANDATORY INSPECTION POINTS ARE EMPLOYED AS APPROPRIATE AT VARIOUS LEVELS OF ASSEMBLY AND TEST. SPAR/GOVERNMENT SOURCE INSPECTION IS ENVOKED ON THE SUPPLIER. RECEIVING INSPECTION VERIFIES THAT THE MARDWARE RECEIVED IS AS IDENTIFIED IN THE PROCUREMENT DOCUMENTS, THAT HO DAMAGE HAS OCCURRED DURING SHIPMENT, AND THAT APPROPRIATE DATA HAS BEEN RECEIVED UTICH PROVIDES ACQUAIT FRACEABILITY INFORMATION AND IDENTIFIES ACCEPTABLE PARTS. PARTS ARE INSPECTED THROUGHOUT MANUFACTURE AND ASSEMBLY AS APPROPRIATE TO THE MANUFACTURING STAGE COMPLETED. THESE IMPRECTIONS INCLUDE, INSPECTION VERIFIES THAT KITTED PARTS ARE CORRECT PRIOR TO ASSEMBLY AND TRACEABILITY INFORMATION RECORDED. UNITS ARE INSPECTED TO THE APPLICABLE SPAR INSPECTION IEST PROCEDURE (1TP) PRIOR TO MOTOR MODULE INTEGRATION. INSPECTIONS INCLUDE GROUNDING CHECKS, CONNECTOR FOR BENT PINS, VISUAL, CLEAMLINESS, INTERCONNECT WIRTOR STC. INTEGRATION OF UNIT TO MOTOR MODULE INSECTIONS INCLUDE GROUNDING CHECKS, CONNECTOR FOR BENT PINS, VISUAL, CLEAMLINESS, INTERCONNECT WIRTOR STC. A TEST READINES REVIEW (TRR) WHICH INCLUDES AN AUDIT OF LOWER TIER INSPECTION COMPLETION, AS BUILT CONFIGURATION VALIDATION TO AS DESIGN ETC., (MANDATORY INSPECTION POINT). A TEST READINES REVIEW (TRR) WHICH INCLUDES VERIFICATION OF TEST PERSONNEL, TEST DOCUMENTS, TEST EQUIPMENT CALIBRATION/ VALIDATION STATUS AND TRADECTION COMPLETION, SUPPLIER AS APPLICABLE, AND THE GOVENMENT REPRESENTATIVE, PRIOR ID THE START OF ANY OUTLING AND THE GOVENMENT REPRESENTATIVE, PRIOR ID THE START OF ANY FOR AND THE GOVENMENT REPRESENTATIVE, PRIOR ID THE START OF ANY PROCEDURE (TETT) ETC. JOINT LEVEL PRE-ACCEPTANCE TEST INSPECTION, INCLUDE AND THERMAL-VAC TESTING, (SPAR/GOVERNMENT REP MANDATORY INSPECTION FEST OF THE PROCEDUR

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PREPARED BY:

MFWG

SUPERCEDING DATE: NONE

DATE: 11 JUL 91

CIL REV: 0

PROJECT: SRMS (-5 MCIU INSTALLED)
ASS'Y NOMENCLATURE: NOTOR MODULE

SYSTEM: MECHANICAL ARM SUBSYSTEM
ASS'Y P/N: 51140E1214 SHEET: 4

FMEA REF.	FHEA REV.	NAME, QTY, & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	HOWR / FUNC. RATIONALE FOR ACCEPTANCE 1/1 CRITICALITY SCREENS: N/A	
4175	0	COMMITATION SCANNER QTY-6 P/N 51140E1295	MODE: ERRATIC COMMUTATION IN PRINE AND BACKUP MODES. CAUSE(S): (1) LOSS OF PLATING ON CODE WHEEL.	AUTOBRAKES ARE APPLIED. ARM COMES TO REST. LOSS OF REGULAR COMMITATION. ABILITY TO START THE JOINT IN PRIME AND BACK-UP MAY BE LOST. ARM MAY TAKE AN UNEXPECTED TRAJECTORY. LOSS OF ALL MODES. WORST CASE UNEXPECTED MOTION. ELECTRICALLY FROZEN. CREW ACTION REQUIRED. REDUNDANT PATHS REMAINING N/A	COMFIGURATION VERIFICATION TO AS DESIGN ETC. JOINT LEVEL ACCEPTANCE TESTING (ATP) INCLUDES AMBINET, VIBRATION AND THEMPAL-VAC TESTING. (SPAR/GOVERNMENT REP MANDATORY INSPECTION POINT). SRMS SYSTEMS INTEGRATION, THE INTEGRATION OF MECHANICAL ARM SUBASSEMBLIES AND THE FLIGHT CABIN EQUIPMENT TO FORM THE SRMS. INSPECTIONS ARE PERFORMED AT EACH PHASE OF INTEGRATION WHICH INCLUDES GROUNDING CHECKS, THRU MIRING CHECKS, WIRING ROUTING, INTERFACE COMMECTORS FOR BENT OR PUSH BACK CONTACTS ETC. SRMS SYSTEMS TESTING - STRONGBACK AND FLAT FLOOR AMBIENT PERFORMANCE TEST. (SPAR/GOVERNMENT REP MANDATORY INSPECTION POINT)	P
					EXTORE :	ATTACHMENT - PAGE 224 OF 471

PREPARED BY:

SUPERCEDING DATE: NONE

DATE: 11 JUL 91

CIL REV: _0

CRITICAL ITEMS LIST

PROJECT: SRMS (-5 MCIU INSTALLED)
ASS'Y NOMENCLATURE: MOTOR MODULE

SYSTEM: MECHANICAL ARM SUBSYSTEM
ASS'Y P/N: 51140E1214 SHEET: 5

FHEA REF.	FMEA REV.	HAME GTY & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END 1TEM	HDWR / FUNC. RATIONALE FOR ACCEPTANCE 1/1 CRITICALITY SCREENS: N/A
4175	C	COMMUTATION SCANNER GTY-6 P/N 51140E1295	MODE: ERRATIC COMMUTATION IN PRIME AND BACKUP MODES. CAUSE(S): (1) LOSS OF PLATING ON CODE WHEEL.	AUTOBRAKES ARE APPLIED. ARM COMES TO REST, LOSS OF REGULAR COMMUTATION. ABILITY TO START THE JOINT IN PRIME AND BACK-UP MAY BE LOST. ARM MAY TAKE AN UNEXPECTED TRAJECTORY. LOSS OF ALL MODES.	FAILURE HISTORY THERE HAVE BEEN NO FAILURES ASSOCIATED WITH THIS FAILURE MODE ON THE SRMS PROGRAM.
			į	WORST CASE UNEXPECTED MOTION. ELECTRICALLY FROZEN, CREW ACTION REGUIRED.	
				REDUNDANT PATHS REMAINING N/A	
					· · · · · · · · · · · · · · · · · · ·
PARED BY		FMG	SUPERCEDING DATE	• NONE	DATE: 11 JUL 91 CIL REV:

PROJECT: SRMS (-5 MCIU INSTALLED)
ASS'Y MOMENCLATURE: MOTOR MODULE

SYSTEM: MECHANICAL ARM SUBSYSTEM ASS'Y P/N: 51140E1214

SHEET: __6

FHEA REF.	FHEA REV.	NAME QTY & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END LIEM	HOUR / FUNC. RATIONALE FOR ACCEPTANCE 1/1 CRITICALITY SCREENS: N/A
4175	0	COMMUTATION SCANNER QTY-6 P/H 51140E1295	MODE: ERRATIC COMMUTATION IN PRIME AND BACKUP MODES. CAUSE(S): (1) LOSS OF PLATING ON CODE WHEEL.	AUTOBRAKES ARE APPLIED. ARM COMES TO REST. LOSS OF REGULAR COMMUTATION. ABILITY TO START THE JOINT IN PRIME AND BACK-UP MAY BE LOST. ARM MAY TAKE AM UNEXPECTED TRAJECTORY. LOSS OF ALL MODES. WORST CASE UNEXPECTED MOTION. ELECTRICALLY FROZEN. CREW ACTION REQUIRED. REDUMDANT PATHS REMAINING N/A	COMPUTER SUPPORTED MODES CAMNOT BE USED TO COMPLETE THE MISSION. DIRECT DRIVE AND BACK-UP MODES REMAIN. IF PAYLOAD IS ATTACHED, THE ARM SHOULD BE MANQUARRED TO A SAFE POSITION FOR PAYLOAD RELEASE. LOSS OF MENT REDUNDANT PAIN RESULTS IN BEING OME FAILURE AMAY FROM INABILITY TO CRADLE ARM. IF WITH SUBSQUENT FAILURES ALL DRIVE MODES ARE LOST, THE ARM MAY BE JETTISONED. CREW HAS ABILITY TO OVERRIDE A SINGLE FAILURE. CREW ACTION USE SINGLE MODE ON OTHER JOINTS TO POSITION ARM FOR JETTISOM. CREW TRAINING THE CREW WILL BE TRAINED TO ALWAYS OBSERVE WHETHER THE ARM IS RESPONDING PROPERLY TO COMMANDS. MISSION CONSTRAINT OPERATE UNDER VERMIER RATES WITHIN 10 FT OF STRUCTURE. AUTO TRAJECTORIES MUST BE OESIGNED TO COME NO CLOSER THAN 5 FT FROM STRUCTURE. THE OPERATOR MUST BE ABLE TO DETECT THAT THE ARM IS RESPONDING PROPERLY TO COMMANDS VIA WINDOW ANO/OR CCTV VIEWS DURING ALL ARM OPERATIONS. ARM SHOULD NOT BE MANEUVERED TO POSITION WHERE JETTISOM CANNOT BE SAFETY PERFORMED. OMESD OFFLINE IN COMPUTER SUPPORTED MODE WITH ELBOW DEMATED DRIVE ALL JOINTS. VERIFY JOINT MOTION OMESD ONLINE INSTALLATION NOME OMESD ONLINE TURNAROUND IN SINGLE MODE DRIVE ALL JOINTS VERIFY JOINT MOTION

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PREPARED BY:

NFMG

SUPERCEDING DATE: HONE

APPROVED BY.

DATE: 11 JUL 91

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