

FMEA NO. <u>4.4.1.1</u> CRITICALITY <u>2/1R</u>		SHUTTLE CCTV CRITICAL ITEMS LIST	UNIT <u>PTU</u> DWG NO. <u>2794822-502,503,504</u> SHEET <u>1</u> OF <u>8</u>
FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE	
Loss of pan right or left electrical function. PTU A1 Pan Stepper Drive. A2 Power Supply Command/Clock Receivers.	No Pan-tilt motion in response to commands. Worst Case: Loss of elbow PTU control prevents stowing the RMS.	<p>DESIGN FEATURES</p> <p>The heritage for the PTU mechanisms is the designs used successfully on the Lunar Rover equipment on the Apollo 15, 16, and 17 missions.</p> <p>All support bearings in the azimuth and elevation axes are conservatively designed when compared to the launch load environment.</p> <p>The design was prepared by a detailed finite element analysis of the structure, taking into account the derating for the fatigue cycles represented by 180 missions. A series of developmental tests were conducted to verify the analytical models for the structure and drive train analyses. Reviews were held at preliminary design and critical design review levels to evaluate the designs and test data.</p> <p>The PTU has been used on 24 missions at four bulkhead locations and at the RMS elbow location without a failure in the drive train, axis support mechanisms, or structure.</p> <p>The mounting provision from the PTU base to the orbiter structure and RMS arm was analyzed for worst-case landing loads and showed adequate margins.</p> <p>BARE BOARD DESIGN (A2)</p> <p>The design of the associated A2 board is constructed from laminated copper-clad epoxy glass sheets (NEMA G-10) Grade FR-4), PER MIL-P-55617A. Circuit connections are made through printed traces which run from point to point on the board surfaces. Every trace terminates at an annular ring. The annular ring surrounds the hole in which a component lead or terminal is located. This ring provides a footing for the solder, ensuring good mechanical and electrical performance. Its size and shape are governed by MIL-P-55640 as are trace widths, spacing and routing. These requirements are reiterated specifically in drawing notes to further assure compliance. Variations between the artwork master and the final product (due to irregularities of the etching process) are also controlled by drawing notes. This prevents making defective boards from good artwork. Holes which house no lead or terminal, but serve only to electrically interconnect the different board layers, contain stitch bars for mechanical support and increased reliability.</p> <p>The thru holes are drilled from a drill tape thus eliminating the possibility of human error and allowing tight control over hole and annular ring concentricity, an important reliability criterion. After drilling and etching, All copper cladding is tin-lead plated per MIL-STD-1495. This provides for easy and reliable soldering at the time of board assembly, even after periods of prolonged storage.</p>	

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FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE	
Loss of pan right or left electrical function. PTU A1 Pan Stepper Drive. A2 Power Supply Command/Clock Receivers.	No Pan-tilt motion in response to commands. Worst Case: Loss of elbow PTU control prevents stowing the RMS.	<p>DESIGN FEATURES (Continued)</p> <p>BOARD ASSEMBLY DESIGN (A2)</p> <p>All components are installed in a manner which assures maximum reliability. Component leads are pre-tinned, allowing total wetting of solder joints. All leads are formed to provide stress relief and the bodies of large components are staked. Special mounting and handling instructions are included in each drawing required after final assembly. The board is coated with urethane which protects against humidity and contamination.</p> <p>BOARD PLACEMENT</p> <p>The A1, A2 boards are secured in the electronics assembly by gold-plated beryllium copper card guides. Connections are made to the mother board with blind-mated connectors. Disengagement during launch is prevented by a cover which spans the board's free edge.</p> <p>BASE BOARD CONSTRUCTION (A1)</p> <p>The board is of "welded wire" construction. At the bare board level this does not distinguish it from a normal PC board except that holes which will take weld pins generally are not connected to PC traces. Only those pins which bring power and ground potentials to the ICs are on PCs. An annular ring surrounds the hole in the board where each power and ground pin is located. These pins are then soldered to the trace like any other component lead. Aside from this feature, all design & construction techniques used in PC board layout apply.</p> <p>BOARD ASSEMBLY (A1)</p> <p>The drilled and etched boards are populated with several hundred solderable or weldable pins. Power and ground pins, as well as connector pins, are soldered in place. Discrete components (resistors, diodes, capacitors) are attached to bifurcated terminals, where they are soldered. Flatpack ICs are welded, lead-by-lead, to the tops of the weld pins. After welding, extra lead material is trimmed away. Circuit connections are made using #30 AWG nickel weld wire. The wire is welded to the pin surfaces on the board backside. All wire welds are done using a machine which is tape driven, thus eliminating the possibility of miswiring due to operator error. All wiring & circuit performance is tested prior to box-level installation. After successful testing, components are staked as required by drawing notes and the assembly is coated with urethane.</p> <p>The board is inserted in the box on card-edge guides, in the same manner as the other PC boards.</p>	

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CRITICALITY 2/1R

SHUTTLE CTV
CRITICAL ITEMS LIST

UNIT PTU
DWG NO. 2294822-502.503.504
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FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE
<p>Loss of pan right or left electrical function.</p> <p>PTU A1 Pan Slapper Drive. A2 Power Supply Command/Clock Receivers.</p>	<p>No Pan-tilt motion in response to commands.</p> <p>Worst Case: Loss of elbow PTU control prevents stowing the RMS.</p>	<p><u>QUALIFICATION TEST</u></p> <p>For Qualification Test Flow, see Table 2 located at the front of this book.</p>

FMEA NO. <u>4.4.1.1</u> CRITICALITY <u>2/IR</u>	SHUTTLE CCTV CRITICAL ITEMS LIST	UNIT <u>PTU</u> DWG NO. <u>2294622-502,503,504</u> SHEET <u>4</u> OF <u>8</u>
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FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE
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loss of pan right or left electrical function. PTU A1 Pan Stepper Drive. A2 Power Supply Command/Clock Receivers.	No Pan-tilt motion in response to commands. Worst Case: Loss of elbow PTU control prevents stowing the RMS.	<p>ACCEPTANCE TEST</p> <p>The CCTV systems' PTU is subjected directly, without vibration isolators which might be used in their normal installation, to the following testing:</p> <ul style="list-style-type: none"> • Vibration: <table border="0" style="margin-left: 20px;"> <tr> <td>20-80Hz:</td> <td>3 dB/Oct-rise from 0.01 G²/Hz</td> </tr> <tr> <td>80-350 Hz:</td> <td>0.04 G²/Hz</td> </tr> <tr> <td>350-750 Hz:</td> <td>-1 dB/10 Oct-slope</td> </tr> <tr> <td>Test Duration:</td> <td>1 Minute per Axis</td> </tr> <tr> <td>Test Level:</td> <td>6.6 Grms</td> </tr> </table> • Thermal Vacuum: In a pressure of 1x10⁻⁵ torr, the temperature shall be as follows: <table border="0" style="margin-left: 20px;"> <tr> <td>125° F:</td> <td>Time to stabilize equipment plus 1 hour</td> </tr> <tr> <td>25° F:</td> <td>Time to stabilize equipment plus 1 hour</td> </tr> <tr> <td>125° F:</td> <td>Time to stabilize equipment plus 1 hour</td> </tr> </table> <p>The PTU may not have been subjected to the vacuum condition.</p> <p>For Acceptance Test Flow, see Table 1 located at the front of this book.</p> <p>OPERATIONAL TESTS</p> <p>IN ORDER TO VERIFY that CCTV components are operational, a test must verify the health of all the command related components from the PMS (A7A1) panel switch, through the ACU, through the sync lines to the Camera/PTU, to the Camera/PTU command decoder. The test must also verify the camera's ability to produce video, the YSU's ability to route video, and the monitor's ability to display video. A similar test would be performed to verify the ROM command path.</p> <p><u>Pre-Launch on Orbiter Test/In-Flight Test</u></p> <p>(NOTE: In-Flight testing of the elbow camera/PTU must not be conducted as long as the crit 1/1 interference is present.)</p> <ol style="list-style-type: none"> 1. Power CCTV System. 2. Via the PMS panel, select a monitor as destination and the camera under test as source. 3. Send "Camera Power On" command from PMS panel. 4. Select "External Sync" on monitor. 5. Observe video displayed on monitor. Note that, if video on monitor is synchronized (i.e., stable raster), then this indicates that the camera is receiving composite sync from the ACU and that the camera is producing synchronized video. 6. Send Pan, Tilt, Focus, Zoom, AEC, and GAMMA commands and visually (either via the monitor or direct observation) verify operation. 7. Select downlink as destination and camera under test as source. 8. Observe video routed to downlink. 9. Send "Camera Power Off" command via PMS panel. 10. Repeat Steps 3 through 9, except issue commands via the ROM command path. This proves that the CCTV equipment is operational. 	20-80Hz:	3 dB/Oct-rise from 0.01 G ² /Hz	80-350 Hz:	0.04 G ² /Hz	350-750 Hz:	-1 dB/10 Oct-slope	Test Duration:	1 Minute per Axis	Test Level:	6.6 Grms	125° F:	Time to stabilize equipment plus 1 hour	25° F:	Time to stabilize equipment plus 1 hour	125° F:	Time to stabilize equipment plus 1 hour
20-80Hz:	3 dB/Oct-rise from 0.01 G ² /Hz																	
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125° F:	Time to stabilize equipment plus 1 hour																	
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FMEA NO. <u>4.4.1.1</u>		SHUTTLE CCTV CRITICAL ITEMS LIST	UNIT <u>PTU</u>
CRITICALITY <u>2/IR</u>			DWG NO. <u>2294822-502, 503, 504</u>
FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE	
<p>Loss of pan right or left electrical function.</p> <p>PTU A1 Pan Stepper Drive. A2 Power Supply Command/Clock Receivers.</p>	<p>No Pan-tilt motion in response to commands.</p> <p><u>Worst Case:</u> Loss of elbow PTU control prevents stowing the RMS.</p>	<p><u>QA/INSPECTION</u></p> <p><u>Procurement Control</u> - The PTU EEE Parts and hardware items are procured from approved vendors and suppliers, which meet the requirements set forth in the CCTV contract and Quality Plan Work Statement (WS-2593176). Resident DCAS personnel review all procurement documents to establish the need for GSI on selected parts (PAI 517).</p> <p><u>Incoming Inspection and Storage</u> - Incoming Quality Inspections are made on all received materials and parts. Results are recorded by lot and retained in file by drawing and control numbers for future reference and traceability. All EEE parts are subjected to Incoming acceptance tests as called for in PAI 315 - Incoming Inspection Test Instructions. Incoming flight parts are further processed in accordance with RCA 1846684 - Preconditioning and Acceptance Requirements for Electronic Parts, with the exception that DPA and PIND testing is not performed. Mechanical items are inspected per PAI 316 - Incoming Inspection Instructions for mechanical items, PAI 305 - Incoming Quality Control Inspection Instruction, and PAI 612 - Procedure for Processing Incoming or Purchased Parts Designated for Flight Use. Accepted items are delivered to Material Controlled Stores and retained under specified conditions until fabrication is required. Non-conforming materials are held for Material Review Board (MRB) disposition. (PAI 307, PAI IQC-531).</p> <p><u>Board Assembly & Test</u> - Prior to the start of PTU board assembly, all items are verified to be correct by stock room personnel, as the items are accumulated to form a kit. The items are verified again by the operator who assembles the kit by checking against the as-built-parts-list (AUPLI). DCAS Mandatory Inspection Points are designated for all printed circuit, wire wrap and welded wire boards, plus harness connectors for soldering wiring, crimping, solder splices and quality workmanship prior to coating of the component side of boards and sleeving of harnesses.</p> <p>Specific PTU board assembly and test instructions are provided in drawing notes, and applicable documents are called out in the Fabrication Procedure and Record (FPR-2294822) and parts list PL 2294822. These include wire connection List 2295901, Process Standard RTU-566 228081, Process Standard - Bonding eltro Tape 228089, Specification Soldering 2280749, Specification Name Plate Application 1960167, Specification - Crimping 2280800, Specification - Bonding and Staking 2280878, Specification - Urethane coating 2280877, Specification - locking compound 2026116, Specification Epoxy Adhesive 2D10985, Specification - Marking 2280876, Specification-Workmanship 8030035, Specification Bonding and Staking 2280875.</p>	

INEA NO. <u>4.4.1.1</u> CRITICALITY <u>2/1R</u>	SHUTTLE CCTV CRITICAL ITEMS LIST	UNIT <u>PTU</u> DWG NO. <u>2294822-502,503,504</u> SHEET <u>6</u> OF <u>8</u>
FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE
<p>Loss of pan right or left electrical function.</p> <p>LEM</p> <p>A1 Pan Stepper Drive.</p> <p>A2 Power Supply Command/Clock Receivers.</p>	<p>No Pan-tilt motion in response to commands.</p> <p>Worst Case: Loss of elbow PTU control prevents stowing the RMS.</p>	<p><u>QA/INSPECTION (Continued)</u></p> <p><u>PTU Assembly and Test</u> - An open box test is performed per TP-IT-2294822, and an Acceptance Test per TP-AT-2294822, including vibration and thermal vacuum. Torques are specified and witnessed, traceability numbers are recorded and calibrated tools are checked prior to use. RCA Quality and DCAS inspections are performed at the completion of specified FPR operations in accordance with PAI-204, PAI-205, PAI 206 and PAI 217. DCAS personnel witness PTU button-up and critical torquing. RCA QC and DCAS personnel monitor acceptance tests and review the test data/results. These personnel also inspect for conformance after all repair, rework and retest.</p> <p><u>Preparation for Shipment</u> - The PTU is packaged according to CCTV Letter 8011 and 2280746, Process standard for Packaging and Handling guidelines. All related documentation including assembly drawings, Parts List, ABPL, Test Data, etc, is gathered and held in a documentation folder assigned specifically to each assembly. This folder is retained for reference. An EIDP is prepared for each PTU in accordance with the requirements of MS-2593176. RCA QC and DCAS personnel witness crating, packaging, packing and marking, and review the EIDP for completeness and accuracy.</p>

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 CRITICALITY 2/1R

SHUTTLE DCTV
 CRITICAL ITEMS LIST

UNIT PTU
 DWG NO. 2294822-502.503.504
 SHEET 7 OF 8

FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE
<p>Loss of pan right or left electrical function.</p> <p>PII A1 Pan Stepper Drive. A2 Power Supply Command/Clock Receivers.</p>	<p>No Pan-tilt motion in response to commands.</p> <p>Worst Case: Loss of elbow PTD control prevents stowing the RMS.</p>	<p><u>FAILURE HISTORY</u> NONE.</p>

FMEA NO. <u>4411</u> CRITICALITY <u>2/1R</u>		SHUTTLE CCTV CRITICAL ITEMS LIST	UNIT <u>PTU</u> DWG NO. <u>2294822-502,503,504</u> SHEET <u>B</u> OF <u>B</u>
FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE	
Loss of pan right or left electrical function. EIU A1 Pan Slepper Drive. A2 Power Supply Command/Clock Receivers.	No Pan-tilt motion in response to commands. Worst Case: Loss of elbow PIU control prevents stowing the RMS.	<p><u>OPERATIONAL EFFECTS</u></p> <p>Loss of ability to position the elbow camera. Possible inability to stow the RMS if the elbow camera physically interferes with a payload. If RMS cannot be stowed the port payload bay door cannot be closed. Loss of crew and vehicle.</p> <p><u>CREW ACTIONS</u></p> <p>Perform EVA to reposition the elbow camera, use RMS motion to reposition the camera, or jettison the RMS.</p> <p><u>CREW TRAINING</u></p> <p>Crew should be trained in contingency EVA and RMS operations procedures.</p> <p><u>MISSION CONSTRAINT</u></p> <p>Do not manifest elbow camera for any flight where the payload and the elbow camera can interfere with each other (for any pan or tilt angle). If the camera must be flown do not change the camera position until the interfering payload is deployed.</p>	