PROJECT: SRMS ASS'Y HOMENCLATURE: BACK-UP

| FREA | | HAVE, GTY, & | | ASS'Y NOMENCLATURE: | BACK-UP ASS'Y P/N: SHEET: |
|------|------|---|---|--|---|
| REF. | REV. | DRAWING RÉF. DESIGNATION | FATLURE MODE AND CAUSE | FATLURE EFFECT ON END LIEN | HOUR / FUNC. 1/1 RATIONALE FOR ACCEPTANCE CRITICALITY |
| 4560 | 0 | PULSE WIDTH MODULATOR SCHEMATIC 2559039 GTY-1 | MODE: INCORRECT OUTPUT FROM PIM. CAUSE(\$): (1) PARTS FAILURE. | THE OUTPUT TO INE MOTOR WILL NOT BE AS DEMANDED AND MAY RESULT IN MOTOR ORIVING IN OPPOSITE DIRECTION TO COMMAND. WORST CASE UMEXPECTED MOTION. WRONG JOINT ON WRONG LATED. CREW ACTION REGUIRED. REDUNDANT PATHS REMAINING | COMPARATORS AND OPERATIONAL AMPLIFIERS ARE STANDARD LINEAR INTEGRATED CIRCUITS WITH MATURE MANUFACTURING TECHNOLOGY. APPLICATION CONSTRAINTS ARE IN ACCORDANCE WITH SPAR-RMS-PA.003. ALL RESISTORS AND CAPACITORS USED IN THE DESIGN ARE SELECTED FROM ESTABLISHED RELIABILITY (ER) TYPES. LIFE EXPECTANCY IS INCREASED BY ENSURING THAT ALL ALLOMABLE STRESS LEVELS ARE DERATED IN ACCORDANCE WITH SPAR-RMS-PA.003. ALL CERAMIC AND ELECTROLYTIC CAPACITORS ARE ROUTINELY SUBJECTED TO RADIOGRAPHIC INSPECTION. THE DESIGN UTILIZES PROVEN CIRCUIT TECHNIQUES AND IS IMPLEMENTED USING CHOS LOGIC DEVICES. CHOS DEVICES OPERATE AT LOW POWER AND HENCE DO NOT EXPERIENCE SIGNIFICANT OPERATING STRESSES. THE TECHNOLOGY IS MATURE, AND DEVICE RELIABILITY HISTORY IS WELL DOCUMENTED. ALL STRESSES ARE ADDITIONALLY REDUCED BY DERATING THE APPROPRIATE PARAMETERS IN ACCORDANCE WITH SPAR-RMS-PA.003. SPECIAL HANDLING PRECAUTIONS ARE USED AT ALL STAGES OF MANUFACTURE TO PRECLUDE DAMAGE/STRESS DUE TO ELECTROSTATIC DISCHARGE. |
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PREPARED BY: MFMG

SUPERCEDING DATE: 11 SEP 86

APPROVED BY:

PROJECT: SRMS ASS'Y NOMENCLATURE: BACK-UP SYSTEM: BACK-UP

| REF. | REV. DRAWING REF. DESIGNATION | FAYLURE MODE AND CAUSE | FATLURE EFFECT ON END ITEM | ASS'Y P/N: SHEET: HOUR / FUNC. 1/1 RATIONALE FOR ACCEPTANCE |
|------|---|--|--|--|
| 4560 | PULSE WIDTH MODULATOR SCHEMATIC 2559039 GTY-1 | NODE: INCORRECT OUTPUT FROM PAM. CAUSE(S): (1) PARTS FAILURE. | THE OUTPUT TO THE MOTOR WILL MOT BE AS DEMANDED AND MAY RESULT IN MOTOR DRIVING IN OPPOSITE DIRECTION TO COMMAND. MORST CASE UMEXPECTED MOTION. MRONG JOINT DIRECTION. UMANUSHISTED. CREW ACTION REQUIRED. REPUMBANT PATHS RERAINING N/A | ACCEPTANCE TESTS THE BBA IS ACCEPTANCE TESTED FOR THE FOLLOWING ENVIRONMENTS AS AN SRU. O VIBRATION: LEVEL AND DURATION - REFERENCE TABLE 4 O THERMAL: +70 DEGREES C TO - 25 DEGREES C (1 1/2 CYCLES) THE BBA IS INTEGRATED INTO THE SHOULDER JOINT AND EXPOSED TO THE JOINT ACCEPTANCE FINVIRGHMENTS (VIBRATION AND THERMAL VACUUM). THE SHOULDER JOINT IS THEREAFTER TESTED AS PART OF THE RMS SYSTEM TESTS (TPSTB RMS STRONGBACK AND TPS52 FLAT FLOOR TESTS) MHICH VERIFIES THE ABSENCE OF THE FAILURE MODE. GUALIFICATION TESTS THE BDA HAS BEEN QUALIFICATION TESTED TO THE FOLLOWING ENVIRONMENTS AS AN SRU. THE BDA IS FUTTHER TESTED ON THE SHOULDER JOINT QUALIFICATION TESTING. D VIBRATION: LEVEL AND DURATION - REFERENCE TABLE 4 O SHOCK: 20G/11MS - 3 AXES (6 DIRECTIONS) O THERMAL: +81 DEGREES C TO -36 DEGREES C (6 CYCLES) 1 X 10°*6 TORR. O HUMIDITY: TEST IN SHOULDER JOINT HUMIDITY TEST O EMC: MIL STO -461 AS MODIFIED BY SL E-0002 (TESTS CEO1, CEO3, CSO1, CSO2, CSO6, RE01, FLIGHT CHECKOUT PDRS OPS CHECKLIST (ALL VEHICLES) JSC 16987 |

PREPARED BY: MFMG SUPERCEDING DATE: 11 SEP 86 APPROVED BY:

DATE:

PROJECT: <u>SRMS</u> ASS'Y NOMENCLATURE: <u>BACK-UP</u>

SYSTEM: BACK-UP
ASS'Y P/N: ______ SHEET:

| FNEA REF. | REV. | DRAWING REF. DESIGNATION | FATLURE RODE AND CAUSE | FATLURE EFFECT ON END ITEN | HOUR / FUNC: 1/1 RATIONALE FOR ACCEPTANCE |
|--------------|------|---|--|---|--|
| 4560 | • | PULSE MIDTH MODULATOR SCHEMATIC 2559039 OTY-1 | MODE: INCORRECT OUTPUT FROM PAM. CAUSE(S): (1) PARTS FAILURE. | THE OUTPUT TO THE MOTOR WILL MOT BE AS DEMANDED AND MAY RESULT IN MOTOR DRIVING IN OPPOSITE DIRECTION TO COMMAND. WORST CASE UNEXPECTED MOTION. WRONG JOINT DIRECTION CREW ACTION REQUIRED. REDUNDANT PATHS REMAINING M/A | CRITICALITY CAYINSPECTIONS UNITS ARE MAMUFACTURED UNDER DOCUMENTED QUALITY CONTROLS. THESE CONTROLS ARE EXERCISED TUROUGHOUT DESIGN PROCESSING, PABRICATION, ASSEMBLY, TESTING AND SHIPPING OF THE UNITS. MAMDAIDRY IMSPECTION POINTS ARE EMPLOYED AT VARIOUS STAGES OF FABRICATION ASSEMBLY, TESTING AND SHIPPING OF THE UNITS. MAMDAIDRY IMSPECTION IS INVOKED AT VARIOUS CONTROL LEVELS. EEEF PARTS INSPECTION IS PERFORMED AS REQUIRED BY SPAR-BMS-PA. 003. EACH EEE PART IS QUALIFIED AT THE PART LEVEL TO THE REQUIREMENTS OF THE PART IS QUALIFIED AT THE PART LEVEL TO THE REQUIREMENTS OF ADDRESSING BY THE SUPPLIER AND INTIONALLY, REQUIRED BY PAPAR RHS-PA. 003. BEACH EEE PART IS QUALIFIED AT THE PART LEVEL TO THE REQUIREMENTS OF AN INSPECTION OF BRITCH AND BURNED IN, AS A MINIMUM, AS REQUIRED BY PAPAR RHS-PA. 00 BURNED IN, AS A MINIMUM, AS REQUIRED BY PAPAR RHS-PA. 00 BURNED IN ACCORDANCE WITH REQUIREMENTS, BY AN INSPERIMENT SPAR APPROVED TESTING FACILITY. DPA IS PERFORMED AS REQUIRED BY PAPAR RHS-PA. 003. ON A RANDOMLY SELECTED SX OF PARTS, NATIHALD SPIECES, MINIMUM 3 PIECES FOR EACH LOT MAMBER/DATE CODE OF PARTS RECEIVED. MIRE IS PROCURED TO SPECIFICATION MIL-W-22759 OR MIL-W-81381 AND INSPECTED AND TESTED TO MASA JSCHOOLOG STANDARD NUMBER 95A. RECEIVING HISPECTED MY DESTED TO MASA JSCHOOLOG STANDARD NUMBER 95A. RECEIVING HISPECTED MY DESTED TO PARTS DURING SHIPMENT THAT THE RECEIVED ARE AS 10ENTIFIED IN THE PROCUREMENT DURING SHIPMENT THAT THE RECEIVED ARE AS 10ENTIFIED IN THE PROCUREMENT DURING SHIPMENT THAT THE RECEIVED ARE AS 10ENTIFIED TO THE MAMBIFACTURING STAGE COMPLETED. THESE INSPECTIONS INCLUDE, PRINTED CIRCUIT BOARD INSPECTION FOR TRACK SEPARATION, DAMAGE AND COCURRED TO THE MAMBIFACTURING STAGE COMPLETED. THESE INSPECTIONS INCLUDE, PRINTED CIRCUIT BOARD INSPECTION FOR ACCEPTABLE PARTS. COMPONENT MOUNTING INSPECTION FOR ADCOUNTER AND ASSEMBLY AS APPROPRIATE TO THE MAMBIFACTURING STAGE COMPLETED. THESE INSPECTION ALIGNMENT FEP. MANDATORY INSPECTION POINT) P.C. BD. INSTALLATION INSPECTION, CHECK FOR CORRECT |

PREPARED BY: MENG

SUPERCEDING DATE: 11 SEP 86

APPROVED BY: ___

PROJECT: SRMS

ASS'Y HOMENCLATURE: BACK-UP

SHEET:

| REF. | REV. | DRAWING REF. DESIGNATION | FATEURE MODE AND CAUSE | FATLURE EFFECT ON END ITEM | HOLM / FUNC. 1/1 RATIONALE FOR ACCEPTANCE |
|------|------|--|--|---|--|
| 4560 | • | PUR.SE WIDTH HODULATOR SCHEMATIC 2559039 GTY-1 | MODE: INCORRECT OUTPUT FROM PAM. CAUSE(S): (1) PARTS FAILURE. | THE OUTPUT TO THE MOTOR WILL NOT BE AS DEMANDED AND MAY RESULT IN MOTOR DRIVING IN OPPOSITE DIRECTION TO COMMAND. WORST CASE UNEXPECTED MOTION. WRONG JOINT DIRECTION. UNANHUMCIATED. CREW ACTION REQUIRED. REDUNDANT PATHS REMAINING N/A | A TEST READINESS REVIEW (TRR) WHICH INCLUDES VERIFICATION OF TEST PERSONNEL, TEST DOCUMENTS, TEST EQUIPMENT CALEBRATION, VALIDATION STATUS AND MARDMARE CONFIGURATION IS CONVENED BY QUALITY ASSURANCE IN COMJUNCTION MITH ENGINEERING, RELIABILITY, CONFIGURATION CONTROL, SUPPLIER AS APPLICABLE, AND THE GOVERNMENT REPRESENTATIVE. PRIOR TO THE START OF ANY FORMAL TESTING (ACCEPTANCE OR QUALIFICATION). ACCEPTANCE TESTING (ATP) INCLUDES AMBIENT PERFORMANCE, THERMAL AND VIBRATION TESTING, (SPAR/GOVERNMENT REP. MANDATORY INSPECTION POINT). INTEGRATION OF UNIT TO JOINT SRU. INSPECTIONS INCLUDE GROUNDING CHECKS, CONNECTORS FOR BENT OR PUSHBACK CONTACTS, VISUAL, CLEANLINESS, INTERCONNECT WIRRING AND POWER UP TEST TO THE APPROPRIATE JOINT INSPECTION, INCLUDES AN AUDIT OF LOWER TIER HISPECTION COMPLETION, INCLUDES AN AUDIT OF LOWER TIER HISPECTION COMPLETION, AS BUILT CONFIGURATION VERIFICATION TO AS DESIGN ETC. JOINT LEVEL ACCEPTANCE IS TIME (ATP) INCLUDES AMBINET, VIBRATION AND THERMAL VALCESTING, (SPAR/GOVERNMENT REP. MANDATORY INSPECTION POINT). SRNS SYSTEMS INTEGRATION, THE INTEGRATION OF MECHANICAL ARM SUMBASSEMBLIES AND THE FLIGHT CABIN EQUIPMENT TO FORM THE SRMS. IMSPECTIONS ARE PERFORMED AT EACH PRASE OF INTEGRATION WHICH INCLUDES GROUNDING CHECKS, THRU MIRING CHECKS, WIRING ROUTING, INTERFACE CONNECTIONS OR BENT OR PUSHS RACK CONTACTS ETC. SRNS SYSTEMS TESTING - STRONGBACK AND FLAT FLOOR AMBIENT PERFORMANCE TEST. (SPAR/GOVERNMENT REP. MANDATORY INSPECTION POINT) |

| PREPARED | BY: | MFWG | SUPERCEDING DATE: | 11 SEP 86 | APPROVED BY: | DATES | |
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PROJECT: SRMS
ASS'Y NOMENCLATURE: BACK-UP
SHEET:

| FREA REF. | REV. | DRAWING REF. DESIGNATION | FATLUME MODE AND CAUSE | FATLURE EFFECT ON END LIEM | HOUR / FUNC. 1/1 RATIONALE FOR ACCEPTANCE CRITICALITY |
|--------------|------|---|---|---|---|
| 4560 | 0 - | PULSE WIDTH MODULATOR SCHEMATIC 2559039 QTY-1 | MODE: INCORRECT OUTPUT FROM PUM. CAUSE(S): (1) PARTS FATLURE. | THE OUTPUT TO THE MOTOR WILL MOT BE AS DEMANDED AND MAY RESULT IN MOTOR DRIVING IN OPPOSITE DIRECTION TO COMMAND. | FAILURE HISTORY THERE NAVE BEEN NO FAILURES ASSOCIATED WITH THIS FAILURE MODE ON THE SRMS PROGRAM. |
| | | | | WORST CASE UNEXPECTED MOTION. WRONG JOINT DIRECTION. UMANHANCIATED. CREW ACTION REQUIRED. | |
| | | | | REDUNDANT PATHS REMAINING | |
| | | | i | N/A | |
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PREPARED BY: MENG

SUPERCEDING DATE: 11 SEP 86

APPROVED BY

RMS/BACK-UP 74



PROJECT: SRMS

ASS'Y NOMENCLATURE: BACK-UP

SHEET: 6

| - | | | _ | SS'Y NOMENCLATURE: <u>D</u> | ACK-UP ASS'Y P/N: SHEET: |
|------|------|---|--|---|--|
| REF. | REV. | DRAWING RÉS. DESIGNATION | FATLURE MODE AND CAUSE | FATLURE EFFECT ON END ITEM | HOUR / FUNC. 1/1 RATIONALE FOR ACCEPTANCE CRITICALITY |
| 4560 | 0 | PULSE MIDTH MODULATOR SCHEMATIC 2559039 QTY-1 | MODE: INCORRECT CUTPUT FROM PUM. CAUSE(S): (1) PARTS FAILURE. | THE OUTPUT TO THE MOTOR WILL NOT BE AS BEMANDED AND MAY RESULT IN MOTOR DRIVING IN OPPOSITE DIRECTION TO COMMAND. WORST CASE UNEXPECTED MOTION. WRONG JOINT- DIRECTION. UMANNAMCIATED. CREW ACTION REQUIRED. REDUNDANT PATHS REMAINING | OPERATIONAL EFFECTS WHEN ATTEMPTING TO DRIVE A JOINT IN BACKUP, THE JOINT DRIVE DIRECTION IS OPPOSITE FROM WHAT IS COMMANDED. CREW ACTION REMOVE THE DRIVE COMMAND. CREW TRAINING THE CREW WILL BE TRAINED TO ALWAYS OBSERVE WHETHER THE ARM IS RESPONDING PROPERLY TO COMMANDS. IF IT ISN'T, THE COMMAND SHOULD BE REMOVED. MISSION CONSTRAINT THE OPERATOR MUST BE ABLE TO DETECT THAT THE ARM IS RESPONDING PROPERLY TO COMMANDS VIA WINDOW AND/OR CCTV VIEWS DURING ALL ARM OPERATIONS. |
| | | | | | SCREEN FAILURES N/A OMRSD OFFLINE DRIVE WRIST ROLL IN BACKUP. VERIFY THAT THE JOINT DRIVES AT CORRECT RATE. OMRSD ONLINE INSTALLATION NONE OMRSD ONLINE TURNAROUND DRIVE WRIST ROLL IN BACKUP. VERIFY THAT JOINT DRIVES AT CORRECT RATE. |
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PREPARED BY: MFMG SUPERCEDING DATE: 11 SEP 86 APPROVED BY: DATE:
