Cable 2293995-502 DUG NO. W 11.5 SHUTTLE CCTV FMEA NO. **TSSUED** 10=14-86 CRITECAL ITEMS LIST SHEET CRITICALITY 2/JR FATLURE EFFECT FATLURE NODE AND ON END ITEM RATIONALE FOR ACCEPTANCE CAUSE 1) No video DESIGN FEATURES iss of Sync (negative) 2) No PTU control The Will RVS/PTU cable is a 15-inch long assembly, 16-wire assembly. The cable is en/Short to GND terminated on each end with a 37-pin connector (Pl. KJG6E)4W35SN16). The video and sync Worst Case: wires are shielded #24 Twinax twisted-pair wires. The WI) cable provides power and commands from the remote video switch (RVS) to the RNS albow camera stack and returns No PTU control of elbow: camera which prevents video signals to the RVS. arm stowage. The cable design is taken from the successfully flown Apollo program. The design is a cable-connector assembly in which the wire terminations are protected from excessive flexture at the joint between the wire and the connector terminal. The load concentration is moved away from the conductor connection and distributed axially along the length of the conductors encapsulated in a potted-taper profile. This technique also protects the assembly from dirt and entrapped moisture which could cause problems in space. The cable and its components meet the applicable requirements of NASA. Military and RCA specifications. These requirements include: General/Mechanical/Électrical Features Design and Construction Materials Tarminal Solderability Environmental Qualification Marking and Serialization Traceability and Documentation

REVISED 5-7-87 Cable <u> 229 3395 -502</u> DNG NO. SHUTTLE CCTY FMEA HO. W 11.5 ESSUEÐ 10-14-8**5** CRITICAL ITEMS LIST SHEET CRITICALITY 2/1R TAILURE EFFECT FATEURE MODE AND RATIONALE FOR ACCEPTANCE ON END ITEN CAUSE ll No video QUALIFICATION TEST ss of Sync (negative) 2) Wa PTU control Qualified by 1.) similarity to previous successful space programs and 2.) by use during en/Shart to GND qualification tests of CCTV LRUs. Worst Case: No PIU control of elbow ACCEPTANCE TEST camera which prevents The cable acceptance test consists of an ohometer check to assure that each wire arm stowage. connection is present and intact. Results are recorded on data sheets. OPERATIONAL TEST The following tests verify that CCTV components are operable and that the commands from the PHS (AZAI) panel switch, through the RCO, through the sync lines to the Camera/PTU. to the Camera/PTB command decoder are proper. The tests also verify the camera's ability to produce video, the VSU's ability to route video and the monitor's ability to display video. A similar test verifies the MBN command path. Pre-Launch on Orbiter Test/In-Flight Test Power CCTV System. 2. Select a monitor via the PHS panel, as destination and the camera under test as source. 3. Send "Camera Power On" command from PHS panel. 4. Select "External Symp" on monitor. 5. Observe video displayed on manitar. If video on manitar is synchronized (i.e., stable raster), then this indicates that the camera is receiving composite sync from the RCU and that the camera is producing synchronized video. 6. Send Pan, Tilt, Focus, Zoom, ALC, and Gamma commands and visually (either via the monitor or direct observation) verify proper operation. 7. Select Downlink as destination and camera under test as source. Observe video routed to downlink. 9. Send "Camera Power Off" command via PHS panel. 10. Repeat Steps 3 through 9 except issue commands via the MDM command path. This proves that the CCTV engineent is operational if video is satisfactory.

MEA NO. H 11.5 RITECALITY 2/1R		SHUTTLE COTY CRITICAL TTEMS LIST	DATE CABLE  DWG NO. 2293995-502  1SSUED TO-14-86  SHEET 3 OF 5
AYLURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE	
of Sync (negative) /Short to GMD	1) No PIU control  Marst Case: No PIU control of elbow camera which prevents arm stowage.	Procurement Control - Hire, connectors, solder, etc. are and suppliers which meet the requirements set forth in Plan Work Statement (WS-2593176).  Incoming Inspection & Storage - Incoming Quality inspect materials and parts. Results are recorded by lot and recontrol numbers for future reference and traceability. Material Controlled Stores and retained under specified fabrication is required. Nun-conforming materials are (MRB) disposition. (PAI-307, PAI IQC-53).  Assembly & Test - Prior to the start of assembly, all it by stock room personnel as the items are accumulated to verified again by the operator who assembles the kit by as-built-parts-list (ABPL).  Instructions are given in assembly drawing notes and appreciation are given in assembly drawing notes and appreciation in-line splicing of standard interconnecting will see the second of the	tions are made on all received etained in file by drawing and Accepted items are delivered to conditions until cable held for Material Review Board tems are verified to be correct form a kit. The Items are checking against the holicable documents. These are neacts, 2280001 - Processire using Naychem solder sleeves, es with epoxy colors, 2260876, wallty and DCAS Inspections are complete, the cable assembly is taging and Handling Guidelines. Parts (ist. ABPL, Test Data, etc.

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FMEA NO. M 11.5 CRITICALITY 2/IR		SMUTTLE CCTV CRITICAL ITEMS LIST	UNIT CABLE  DWG NO. 2293995-502  1558ED 10-14-06  SHEET 4 0F 5	
FATLURE HODE AND CAUSE	FAILURE EFFECT ON END ITEM	RATIONALE FOR ACCEPTANCE		
iss of Sync (negative) ien/Short to GND	1) No video 2) No PTU control  Morst Case: No PTU control of elbow camera which prevents arm stowage.	FAILURE HISTORY  There have been no reported failures during RCA testing	g, pre-flight or flight.	

EA NO. <u>W 11.5</u> ITICALITY <u>2/1R</u>		SHUTTLE CCTV CRITICAL ITEMS LIST	URIT Cable UNG NO. 2293995-502 ISSUED 10-14-86 SHEET 5 OF 5	
TEURE MODE AND FAYCURE EFFECT CAUSE ON END LITEM		RATIONALE FOR ACCEPTANCE		
of Sync (negative) Short to GND	1) No video 2) No PTU control  Worst Case:  No PTU control of elbow camera which prevents arm stowage.	OPERATIONAL EFFECTS  Loss of ability to position the Elbow camera. Possible inability to show the RMS if the elbow camera physically interferes with a payload. If RMS cannot be stowed the port payload bay door cannot be closed. Loss of crew and vehicle.  CREM ACTIONS  Perform EVA to reposition the elbow camera, use RMS motion to reposition the camera, or jettison the RMS.  CREW TRAINING  Crew should be trained in contingency EVA and RMS operations procedures.  MISSION CONSTRAINT  Bo not manifest Elbow camera for any flight where the payload and the elbow camera can interfere with each other (for any pan or tilt angle). If the camera must be flown do not change the camera position until the interfering payload is deployed.		